

CS40L5x Schematic and Layout Guidelines

Introduction

The CS40L5x is an advanced haptic driver with waveform memory, integrated DSP, and closed-loop algorithms. This document describes the schematic and layout guidelines for the CS40L51, CS40L52, and the CS40L53 devices.

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1 CS40L5x Pinout

The pinout of the CS40L5x is shown in the Figure below (Top View, through package). Note that the corner pad between Pin 1 and Pin 34 should not be connected externally and should not have any traces, planes, or vias under it.

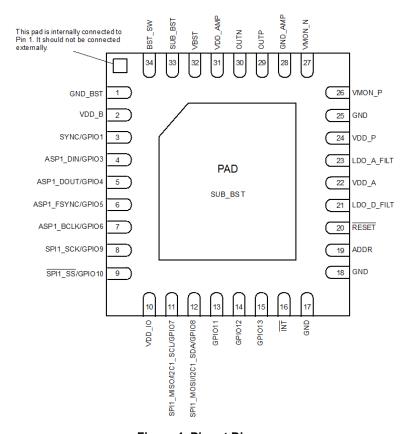


Figure 1 Pinout Diagram



2 CS40L5x Schematic Guidelines

This section describes the different connection configurations that are supported by the CS40L5x device. It covers the different power supply configurations, data and control interfaces, and output and monitoring connections.

There are two typical connections for the CS40L5x device: *internal boost configuration* or *external amplifier supply configuration*. These two configurations are related to the high-power supply connections as described in the <u>High-Current Supply Connections</u> section.

The typical connections for CS40L5x in *internal boost configuration* are shown in the following figure. The optional configurations and allowed selections are provided with their respective notation.

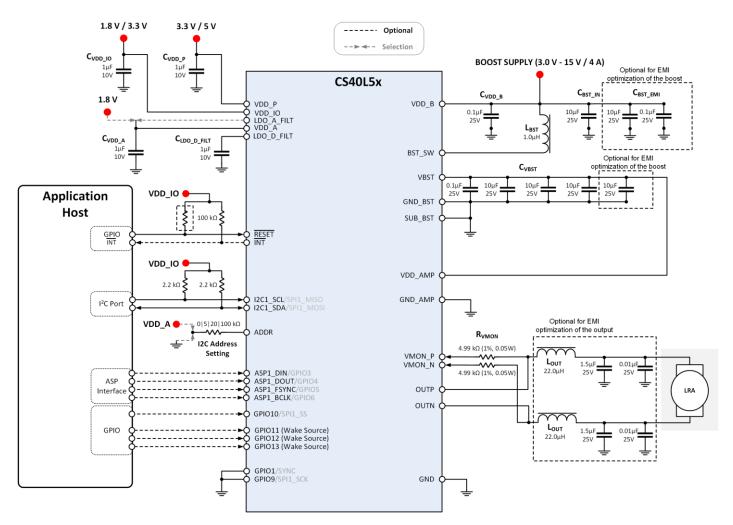


Figure 2 CS40L5x Typical Connection Diagram - Internal Boost



The typical connections for CS40L5x in *external amplifier supply configuration* are shown in the following figure. The optional configurations and allowed selections are provided with their respective notation.

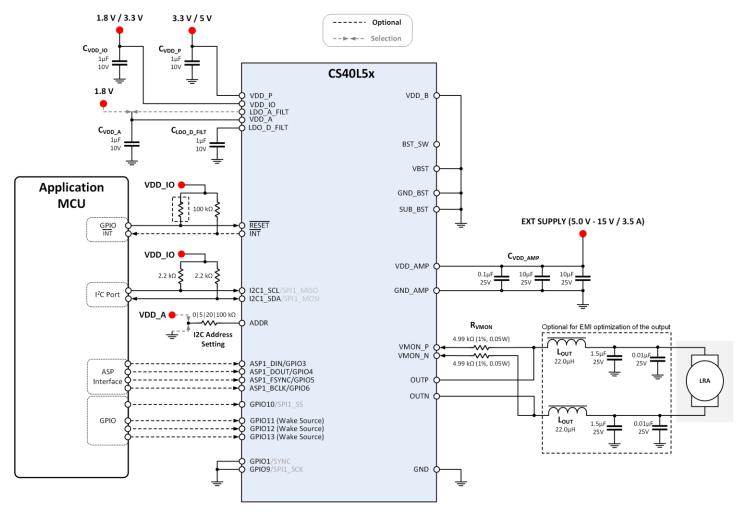


Figure 3 CS40L5x Typical Connection Diagram - External Amplifier Supply



2.1 Recommended External Components

Cirrus Logic recommends the following external components for use with the CS40L5x device.

The recommended external components for CS40L5x in *internal boost configuration* are provided in the following table.

Table 1 Recommended External Components - Internal Boost

Component	Value	Quantity	Manufacturer	Part Number	D	Dimension (mm)		Notes
					L	W	Н	
C _{VDD_P}	1 μF	x1	Taiyo Yuden	LMK105BJ105MVHF	1.0	0.50	0.55	Rated Voltage: 10 V, Temperature Characteristics: X5R
C _{VDD_IO}	1 µF	x1	Taiyo Yuden	LMK105BJ105MVHF	1.0	0.50	0.55	Rated Voltage: 10 V, Temperature Characteristics: X5R
C _{VDD_A}	1 µf	x1	Taiyo Yuden	LMK105BJ105MVHF	1.0	0.50	0.55	Rated Voltage: 10 V, Temperature Characteristics: X5R
C _{LDO_D_FILT}	1 μF	x1	Taiyo Yuden	LMK105BJ105MVHF	1.0	0.50	0.55	Rated Voltage: 10 V, Temperature Characteristics: X5R
C _{VDD_B}	0.1 µF	x1	Samsung	CL05B104KO5VPNC	0.6	0.30	0.3	Rated Voltage: 25 V, Temperature Characteristics: X5R
C _{BST_IN}	10 μF	x1	Taiyo Yuden	EMK212BBJ106KGHT	2.0	1.25	1.35	Rated Voltage: 16 V, Temperature Characteristics: X5R
L _{BST}	1 µH	x1	Murata	LQH44PH1R0MPRL	4.0	4.0	1.8	Rated DC Current: 3.2 A (I_{rms}) / 4.3 A (I_{sat}), DC resistance: 30 m Ω (max)
C _{VBST}	10 μF	х3	Murata	EMK212BBJ106KGHT	2.0	1.25	1.35	Rated Voltage: 16 V, Temperature Characteristics: X5R
C _{VBST}	0.1 µF	x1	Samsung	CL05B104KO5VPNC	1.0	0.50	0.55	Rated Voltage: 16 V, Temperature Characteristics: X7R
R _{VMON}	4.99 kΩ	x2	Vishay Dale	CRCW04024K99FKED	1.0	0.50	0.40	Rated Power: 1/16 W, Tolerance: 1%

The recommended external components for CS40L5x in *external amplifier supply configuration* are provided in the following table.

Table 2 Recommended External Components - External Amplifier Supply

Component	Value	Quantity	Manufacturer	Part Number	D	Dimension (mm)		Notes
					L	W	Н	
C _{VDD_P}	1 µF	x1	Taiyo Yuden	LMK105BJ105MVHF	1.0	0.5	0.55	Rated Voltage: 10 V, Temperature Characteristics: X5R
C _{VDD_IO}	1 μF	x1	Taiyo Yuden	LMK105BJ105MVHF	1.0	0.5	0.55	Rated Voltage: 10 V, Temperature Characteristics: X5R
C _{VDD_A}	1 µf	x1	Taiyo Yuden	LMK105BJ105MVHF	1.0	0.5	0.55	Rated Voltage: 10 V, Temperature Characteristics: X5R
C _{LDO_D_FILT}	1 μF	x1	Taiyo Yuden	LMK105BJ105MVHF	1.0	0.5	0.55	Rated Voltage: 10 V, Temperature Characteristics: X5R
C _{VDD_AMP}	0.1 μF	x1	Samsung	CL05B104KO5VPNC	1.0	0.5	0.55	Rated Voltage: 16 V, Temperature Characteristics: X7R
C _{VDD_AMP}	10 μF	x2	Taiyo Yuden	EMK212BBJ106KGHT	2.0	1.25	1.35	Rated Voltage: 16 V, Temperature Characteristics: X5R
R _{VMON}	4.99 kΩ	x2	Vishay Dale	CRCW04024K99FKED	1.0	0.50	0.40	Rated Power: 1/16 W, Tolerance: 1%



2.2 Power Supply Connections

CS40L5x requires connections to one or two low-current supplies and one high-current supply. The low-current supplies are required for the system supply (VDD_P), digital input/output (VDD_IO), and analog (VDD_A) domains as described in the Low-Current Supply Connections section. The high-current supply is required for the boost converter and/or amplifier as described in the High-Current Supply Connections section.

2.2.1 Low-Current Supply Connections

CS40L5x requires one or two low-current supplies for the system supply (VDD_P), digital input/output (VDD_IO), and analog (VDD_A) domains. Three different configurations for the low-current supply connections provide support for different system topologies.

The system designer should select a power configuration from the table below, and verify the voltage and current requirements in the target application.

Configuration	Power Supply Rail	Voltage	Maximum Current				
Single Supply, 3.3 V IOs	VDD_P	3.3 V (typ)	40 mA				
3.3 V / 1 mA 3.3 V / 40 mA		3.0 - 5.5 V					
3.5 V / TIMA 5.5 V / 40 IMA	VDD_IO	3.3 V (t <i>yp</i>)	1 mA				
C _{VDD_IO} C _{VDD_P}		1.71 - 3.6 V					
1µF 1µF 1	VDD_A	(Internal)	(Internal)				
CS40L5x							
VDD_P							
VDD_IO LDD_A FILT VDD_A							
C _{VDD_A} C _{LDO_D_FILT} CDO_D_FILT							
1μF 10V							
<u></u>							
Dual Supply, 3.3 V IOs	VDD_P	3.3 V (typ)	10 mA				
3.3 V / 1 mA 3.3 V / 10 mA		3.0 - 5.5 V					
5.5 V / TIMA 5.5 V / TO MA	VDD_IO	3.3 V (typ)	1 mA				
C _{VDD_IO} C _{VDD_P}		1.71 - 3.6 V					
1μF	VDD_A	1.8 V (t <i>yp</i>)	30 mA				
<u> </u>		1.71 - 1.89 V					
1.8 V / 30 mA VDD_P VDD IO							
VDD_A LDO_A_FILT VDD_A							
C _{VDD_A} C _{LDO_D_FILT} DO_D_FILT							
1µF 10V + 1µF							
± ±	\(\tag{2} \)	0.01/ 5.01//	10. 4				
Dual Supply, 1.8 V IOs	VDD_P	3.3 V or 5.0 V (typ)	10 mA				
1.8 V / 1 mA 3.3 – 5.0 V / 10 mA	\/DD 10	3.0 - 5.5 V	4 4				
• •	VDD_IO	1.8 V (typ)	1 mA				
C _{VDD_IO} C _{VDD_P}	VDD_A	1.71 - 3.6 V	30 mA				
1μF 10V T CS40L5x	VDD_A	1.8 V (t <i>yp</i>) 1.71 - 1.89 V	30 MA				
= = =		1.71 - 1.09 V					
- V VDD P							
VDD_IO O LDO A FILT VDD_A VDD_A Cup D FILT							
1μF 1μF							
10V T 10V T							
Note: The maximum current shown represents typical test	conditions						
Note: The maximum current shown represents typical test conditions.							

Table 3 Low-Current Supply Requirements



The required decoupling capacitance on each low-power supply rail is 1 µF (typical), as described in the table below. Refer to the <u>Recommended External Components</u> section for part number recommendations.

Component	Min	Тур	Max	Units
C _{VDD_P} Decoupling Capacitance	_	1.0	_	μF
C _{VDD_IO} Decoupling Capacitance	_	1.0	_	μF
C _{VDD_A} Decoupling Capacitance	_	1.0	_	μF
CLDO A FILT Decoupling Capacitance at 1.8V	0.50	1.0		uF

0.39

1.0

μF

Table 4 Low-Current Supply Components

2.2.2 High-Current Supply Connections

GND_AMP

Note: The maximum current shown represents typical test conditions.

CS40L5x requires a high-current supply for the boost converter and/or amplifier. There are two possible configurations for the high-current supply, supporting different system topologies: *internal boost* and *external amplifier supply*.

The system designer should select a power configuration from table below, and verify the voltage and current requirements in the target application.

CLDO_D_FILT Decoupling Capacitance at 1.25 V

Configuration **Power Supply Rail** Voltage **Maximum Current** VDD_B 3.0 - 15 V 20 mA **Internal Boost** BST_SW 3.0 - 15 V 4 A ----- Optional --▶ Selection BOOST SUPPLY (3.0 V - 15 V / 4 A) CS40L5x VDD_E BST SW optimization of the bo VBS1 VDD AMP GND_AMP VDD_AMP **External Amplifier Supply** 5.0 - 15 V 3.5 A ----- Optional CS40L5x VDD_B BST_SW VBST GND_BST SUB_BST EXT SUPPLY (5.0 V - 15 V / 3.5 A) VDD_AMP

Table 5 High-Current Supply Requirements



The component requirements for each configuration are described in the tables below. Refer to the <u>Recommended External Components</u> section for part number recommendations.

Note the CS40L5x boost converter requires a combined de-rated capacitance no less than 2 μ F at 15 V from multiple capacitors (C_{VBST}). The L_{BST} inductor must not de-rate to less than 0.5 μ H during device operation in order to maintain proper loop stability. A L_{BST} boost inductance of 1.0 μ H is recommended.

Table 6 High-Current Supply Components - Internal Boost Configuration

Component	Min	Тур	Max	Units
C _{VBST} Decoupling Capacitance at 15V	2	_	_	μF
L _{BST} Inductance	_	1.0	_	μΗ
Min L _{BST} at peak inductor current	0.5	_	_	μΗ

For the external amplifier supply configuration, the total C_{VDD_AMP} decoupling capacitance must not de-rate less than 2 μ F at 15 V. Refer to the Recommended External Components section for part number recommendations.

Table 7 High-Current Supply Components - External Amplifier Supply Configuration

Component	Min	Тур	Max	Units
C _{VDD_AMP} Decoupling Capacitance at 15V		_		μF

2.2.3 Ground Connections

The following pins must be connected to ground in all configurations. Note that other pins may also be connected to ground, depending on the applicable power configuration - see <u>High-Current Supply Connections</u>. See also <u>GPIO Connections</u> for the required connection for unused GPIOs.

Table 8 Ground Pins Summary

Pin Name	Pin Number	Description
GND	17, 18, 25	Low-power analog and digital ground return
PAD	PAD	Thermal pad ground
SUB_BST	33	Boost substrate ground
GND_BST	1	Boost converter ground reference
GND_AMP	28	Class D amplifier ground reference
GPIO1 / SYNC	3	Unused GPIO (see GPIO Connections)
GPIO9 / SPI1_SCK	8	Unused GPIO (see GPIO Connections)



2.3 Control and Data Connections

The CS40L5x provides a hardware reset pin to turn the device on/off and an I²C interface (control port) to read and write the control registers. Furthermore, four pins are set as GPIs by default and four pins are set as an ASP interface by default (these pins can be reconfigured for GPI trigger purposes). One optional interrupt pin is provided for event notifications to a host. This section describes the requirements for these connections.

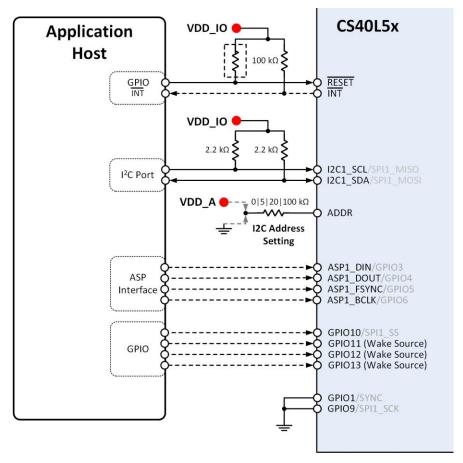


Figure 4 CS40L5x Control and Data Connections Diagram

2.3.1 Reset Connection

The hardware reset pin (RESET) allows turning on and off the CS40L5x device. This pin is connected to a host GPO output pin in a system. An external pull-up resistor to VDD_IO is only required if the host GPO is unable to drive it at all times while CS40L5x has power applied to it. The RESET pin is referenced to VDD_IO logic levels, but is also 5 V tolerant.



2.3.2 I²C Interface Connection

The CS40L5x control port uses an I²C interface to allow reading and writing to the device. The I²C interface is supported using the I2C1_SCL and I2C1_SDA pins; these pins use logic levels referenced to the VDD_IO supply. The CS40L5x is a target device on the I²C bus in a system. The I²C device address is configured using the ADDR pin which allows eight possible addresses.

2.3.2.1 I²C Pull-Up Resistors

The I²C interface requires pull-up resistor to the VDD_IO supply. The pull-up resistor value is determined by the bus capacitance and the minimum drive strength of ICs on the I²C bus. Cirrus Logic recommends I²C pull-up resistors between 2.2 k Ω and 10 k Ω .

Table 9 Recommended I2C Pull-Up Resistors

Component	Min	Тур	Max	Units
I ² C pull-up resistors	_	2.2 to 10		kΩ

2.3.2.2 I2C Device Address

The CS40L5x supports eight I²C device address options; these are selected by connecting ADDR pin to GND or VDD_A through a 0 Ω , 5 k Ω , 20 k Ω , or 100 k Ω resistor as shown in the table below. The external resistance must be within 5% of the specified value.

Note that, in the table below, the specified I²C target device address is an 8-bit value, the LSB contains the R/W bit, e.g., Write address 0x60, Read address 0x61.

External Resistance	Connection Type	I ² C Target Device Addre		
		Write	Read	
0 Ω	Pull-Down to GND	0x60	0x61	
	Pull-Up to VDD_A	0x62	0x63	
5 kΩ	Pull-Down to GND	0x64	0x65	
	Pull-Up to VDD_A	0x66	0x67	
20 kΩ	Pull-Down to GND	0x68	0x69	
	Pull-Up to VDD_A	0x6A	0x6B	
100 kΩ Pull-Down to GNI		0x6C	0x6D	
	Pull-Up to VDD_A	0x6E	0x6F	

Table 10 I2C Device Address Selection



2.3.3 ASP Interface Connection

The CS40L5x has four pins configured for the ASP interface by default. These pins can be configured as GPIO pins if needed.

Table 11 ASP Interface (GPIO) Pins Summary

Pin Name	Pin Number	Default State	System Connection	Unused Connection
ASP1_DIN/GPIO3	4	Input, passive pull down	Connect to host GPO output pin (VDD_IO level) *	Not connected or connect to GND #
ASP1_DOUT/GPIO4	5	Output, passive pull down	Connect to host GPO output pin (VDD_IO level) *	Not connected or connect to GND #
ASP1_FSYNC/GPIO5	6	Input, passive pull down	Connect to host GPO output pin (VDD_IO level) *	Not connected or connect to GND #
ASP1_BCLK/GPIO6	7	Input, passive pull down	Connect to host GPO output pin (VDD_IO level) *	Not connected or connect to GND #

Notes:

A test point is recommended to enable ASP interface for tuning and debugging purposes

2.3.4 GPIO Connections

The CS40L5x has four default GPIs available to trigger haptic effects based on their rising / falling edge. These pins are connected to host GPO output pins at VDD_IO level for operation in a system. If these pins are not used, the "Unused Connection" recommendation must be followed.

Table 12 GPIO Pins Summary

Pin Name	Pin Number	Default State	System Connection	Unused Connection
SPI1_SS/GPIO10	9	Input, Hi-Z	Connect to host GPO output pin (VDD_IO level) *	Connect to VDD_IO
GPIO11	13	Input, Hi-Z	Connect to host GPO output pin (VDD_IO level) ^	Connect to GND
GPIO12	14	Input, Hi-Z	Connect to host GPO output pin (VDD_IO level) ^	Connect to GND
GPIO13	15	Input, Hi-Z	Connect to host GPO output pin (VDD_IO level) ^	Connect to GND

Notes:

2.3.5 Interrupt Connection

The CS40L5x provides an interrupt pin (INT) for event notifications to a host. This GPO pin is an open-drain output, and an external pull-up resistor is required. The INT pin is connected to a host GPI interrupt input pin at VDD_IO level for operation in a system.

Table 13 Interrupt Pin Requirement

	Pin Name	Pin Number	System Connection	Unused Connection		
I	INT	16	Connect to host GPI interrupt input pin (VDD_IO level)	Connect to a 100 kΩ pull-up resistor to VDD_IO		
			Connect to a 100 kΩ pull-up resistor to VDD_IO			

^{*} Non-wake up GPI trigger - Cannot wake device up from hibernate state

^{*} Non-wake up GPI trigger - Cannot wake device up from hibernate state

[^] Wake up GPI trigger - Can wake device up from hibernate state



2.4 Output and Monitoring Connections

The CS40L5x provides a high-performance Class D differential output for a direct connection to a haptic actuator. The CS40L5x contains dedicated voltage-monitor pins to track the voltage across the haptic actuator input.

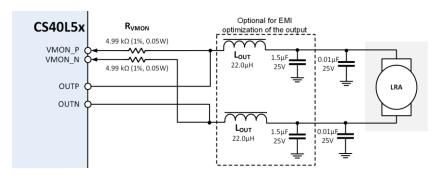


Figure 5 CS40L5x Output and Monitoring Connections Diagram

2.4.1 Output Connections

The CS40L5x output pins, OUTP and OUTN, are connected to Linear Resonant Actuator (LRA) or Voice Coil Motor (VCM) with an impedance as low as 4 Ω and a resonant frequency in the 50 Hz - 561 Hz range.

Table 14 Haptic Output Characteristics - Supported Actuators

	Min	Тур	Max	Units
Load Resistance	4	8	_	Ω
Resonant Frequency	50		561	Hz

2.4.2 Monitoring Connections

The CS40L5x voltage monitor pins, VMON_P and VMON_N, must be connected with series resistors to OUTP and OUTN respectively; these connections should be as close as possible to the haptic actuator (LRA/VCM). Both resistors must be $4.99 \text{ k}\Omega$, 1/20 W power rating and 1% tolerance for optimal performance.

Table 15 Monitoring Resistors

Component	Min	Тур	Max	Units
R _{VMON} series resistors	_	4.99	_	kΩ



2.5 EMI Filtering

Depending on the application, additional filters may be used to suppress EMI. These optional filters can be added on the input supply and to the output signals.

2.5.1 Input Supply Filter

A filter may be added to the input supply to provide additional EMI optimization.

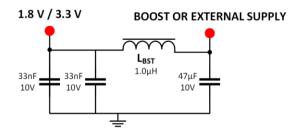


Figure 6 Input Supply Filter Schematic

2.5.2 Boost Supply Filter

For the internal-boost supply configuration, a filter can be added for EMI optimization.

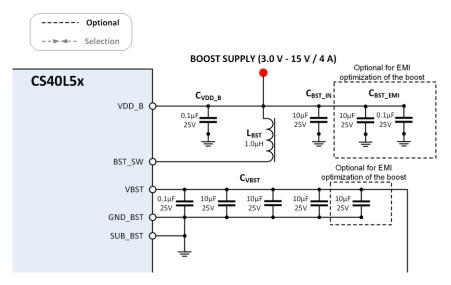


Figure 7 Boost Supply Filter Schematic



2.5.3 Output EMI Filter

The Class D amplifier switching causes radiated emissions on the output lines. The output connections can be optimized for EMI using an L-C filter circuit to reduce the switching noise. The optional filter circuit is shown below.

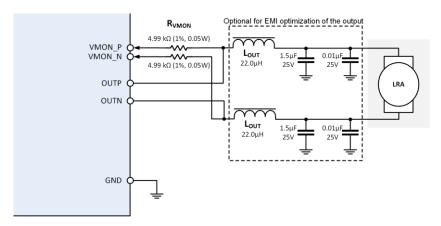


Figure 8 Output Filter Schematic

3 CS40L5x Layout Guidelines

This section describes the recommended routing for power supplies, data and control signals, and output and monitoring signals from a CS40L5x device. Component placement guidelines for the external BOM are also provided.

The following generic board layout guidelines are recommended.

- 1. Four-layer PCB with the following stack up:
 - Layer 1 (top): Component placement and signal routing
 - Layer 2: Reference ground plane
 - Layer 3: Power planes
 - Layer 4 (bottom): Signal routing
- 2. Avoid routing digital signals between power planes on an adjacent layer
 - If signals have to cross on adjacent layers, it is recommended they should cross perpendicular in order to prevent coupling
- 3. Use controlled 50 Ω characteristic impedance for all digital signals
- 4. Avoid routing analog and digital signals next to each other

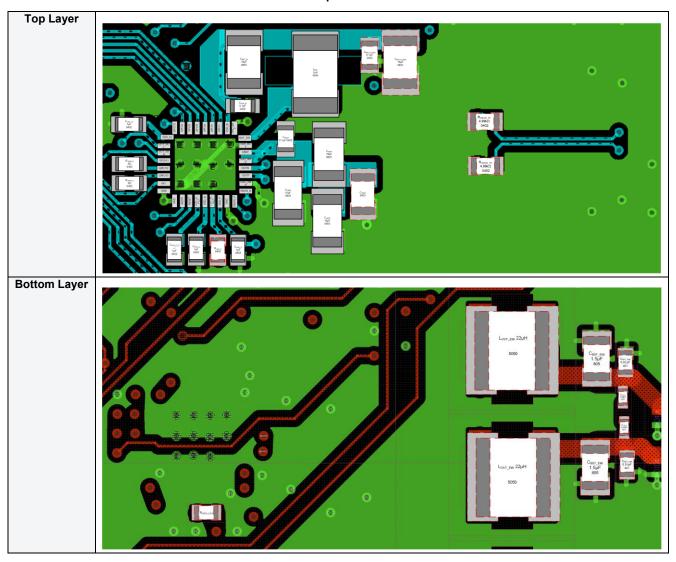
More layers may be required for a particular system. This would not impact the device as long as the recommendations above are followed. The second layer must be the reference ground plane.



3.1 Recommended Component Placement

The recommended component placement for CS40L5x in *internal boost configuration* is shown in the following figure. Optional components are shown in red, dashed outlines.

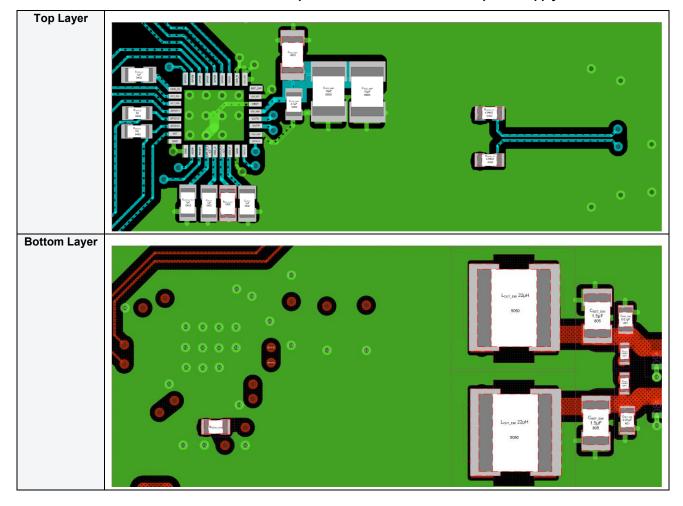
Table 16 Recommended Component Placement - Internal Boost





The recommended component placement for CS40L5x in external amplifier supply configuration is shown in the following figure. Note this example shows the R_{VMON} resistors on the bottom layer, but they can equally be placed on the top layer.

Table 17 Recommended Component Placement - External Amplifier Supply





3.2 Power Supply Routing

The routing and component placement for low-power supplies (VDD_P, VDD_IO, VDD_A) are described in the <u>Low-Current Supply Routing</u> section. The high-power supply routing and component placement guidelines are described in the <u>High-Current Supply Routing</u> section.

3.2.1 Low-Current Supply Routing

The following routing and component-placement guidelines are recommended for the low-current supplies (VDD_P, VDD_IO, VDD_A). The same guidelines are also applicable for the LDO_A FILT and LDO_D FILT pins.

- 1. Place decoupling capacitors on the same PCB side as the CS40L5x device, e.g. top layer.
- 2. Place decoupling capacitors as close as possible to the corresponding pin.
- 3. Use low-current power traces to the system power supply (1 mA 40 mA) or a via to the corresponding power plane. Refer to the Low-Current Supply Connections section for maximum current consumption in each rail.
- 4. Add a via to reference ground plane close to each capacitor's ground pad.

A typical layout for the low-current supply components is shown in the figure below. Note that some vias are located within the pads of the passive components.

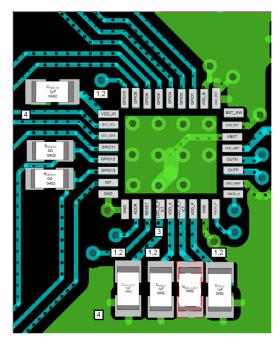


Figure 9 Low-Current Supply Routing and Component Placement



3.2.2 High-Current Supply Routing

3.2.2.1 Internal Boost Configuration

If the CS40L5x is used in the *internal boost* configuration, the following routing and component placement guidelines are recommended for the high-power supplies (BST_SW, VBST, VDD_AMP, and VDD_B) and ground return paths (GND_BST and GND_AMP).

- 1. Place all the components on the same PCB side as the CS40L5x device (e.g. top layer).
- 2. Place L_{BST} inductor as close as possible to the BST_SW pin.
- 3. Use a very short and wide trace to connect inductor to BST_SW pin (4 A high current path).
- 4. Place C_{VDD B} decoupling capacitor (0.1uF) as close as possible to VDD B and GND BST pins.
- 5. Add a via to reference ground plane close to CVDD B capacitor's ground pad.
- 6. Place C_{BST_IN} decoupling capacitor (10uF) as close as possible to inductor and GND_BST pin.
- 7. Add a via to reference ground plane close to **C**_{BST_IN} capacitor's ground pad.
- 8. Use a short but wide local ground plane to connect GND_BST pin to CVDD_B and CBST_IN capacitors.
- 9. Place at least two vias to reference ground plane as close as possible to GND_BST pin. This is a high current ground return path for VBST (4 A).
 - The distance between these vias and the C_{VBST} capacitors' ground vias must be minimized See point 15 below.
- 10.Use a low-current trace (20 mA) to connect VDD_B to CVDD_B decoupling capacitor and power source.
- 11.Connect L_{BST} inductor to power source with a wide trace or plane (4 A high current path). Use at least 4 vias if connecting to a power plane in a different layer. For optimum performance, the DC resistance of the trace or plane from the power source to the inductor should be as low as possible (20 mΩ).
- 12. Connect VBST and VDD_AMP together at the pins (3 A high current path).
- 13. Place C_{VBST} decoupling capacitors as close as possible to VBST and VDD_AMP pins where:
 - a. 0.1uF capacitor is the closest to VBST and GND_BST pins.
 - b. One 10uF capacitor is close to VDD AMP and GND AMP.
- 14. Use a small local ground plane to connect C_{VBST} capacitors' ground pads.
- 15.Place two vias to reference ground plane close to the 0.1uF **C**_{VBST} capacitor's ground pad.

 The distance between these vias and the GND_BST pin's vias must be minimized See point 9 above.
- 16.Add a via to reference ground plane close to each CVBST capacitor's ground pad.
- 17. Place one via close to GND_AMP pin to connect to reference ground plane.

A typical layout for the high-current supply components is shown in the figure below. Note that some vias are underneath the pads of the components.

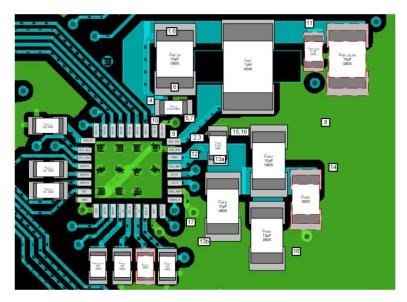


Figure 10 High-Current Supply Routing and Component Placement - Internal Boost



3.2.2.2 External Amplifier Supply Configuration

If the CS40L5x is used in the *external amplifier supply* configuration, the following routing and component placement guidelines are recommended for the high-power supply (VDD_AMP) and ground return path (GND_AMP). Guidelines are also provided for the unused pins (BST_SW, VBST, VDD_B, and GND_BST).

- 1. Place the C_{VDD AMP} decoupling capacitors on the same PCB side as the CS40L5x device, e.g. top layer.
- 2. Place the **C**_{VDD_AMP} decoupling capacitors as close as possible to the VDD_AMP and GND_AMP pins. The 0.1uF capacitor should be closest to VDD_AMP and GND_AMP pins.
- 3. Connect VDD_AMP with a wide trace or plane to external connector or power source (3.5 A high current path). Use at least three vias if connecting to a power plane in a different layer.
- 4. Connect GND_AMP with a wide trace to external connector or power source ground (3.5 A high current path). Use at least three vias if connecting to a plane in a different layer.
- 5. Place one or two vias close to GND AMP pin to connect to reference ground plane.
- 6. Add a via to reference ground plane close to each capacitor's ground pad.
- 7. Connect VBST and SUB BST together at the pins.
- 8. Connect VDD B and GND BST to reference ground plane.

A typical layout for the high-current supply components is shown in the figure below.

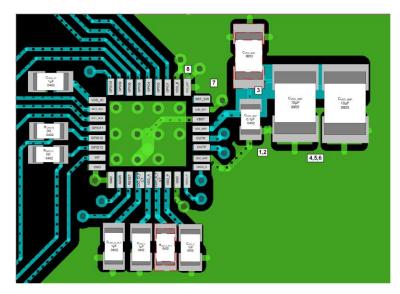


Figure 11 High-Current Supply Routing and Component Placement - External VDD AMP



3.2.3 Ground Routing

The following routing and placement guidelines are recommended for a good ground reference for a CS40L5x device.

- 1. Use a solid reference ground plane on the layer underneath the device, e.g. CS40L5x is placed on layer 1 and solid ground plane is on layer 2.
- 2. Place 12 thermal vias on the thermal ground pad to reference ground plane.
- 3. Connect SUB_BST pin to the thermal ground pad directly on the same layer.
- 4. Place a via close to each ground pin (pins 17, 18, 25) to connect the low-power analog and digital grounds to reference ground plane.

A typical layout for the ground routing is shown in the figure below.

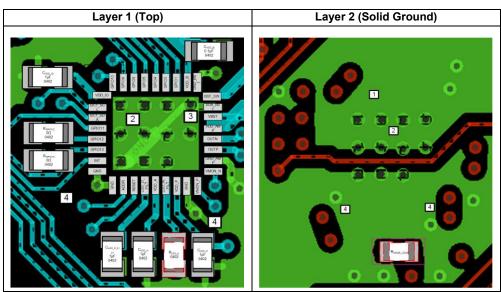


Table 18 Ground Routing



3.3 Control and Data Routing

3.3.1 Reset Routing

The RESET trace must be routed following standard layout practices for digital switching signals.

- 1. Use controlled 50 Ω characteristic impedance if possible.
- 2. Avoid routing the RESET trace between power planes on an adjacent layer. If signals have to cross on adjacent layers, it is recommended they should cross perpendicular in order to prevent coupling.
- 3. Avoid routing the RESET trace next to analog or digital switching signals.

A typical layout for the RESET pin routing is shown in the figure below.

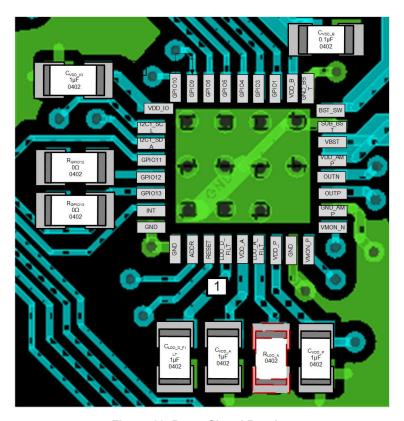


Figure 12 Reset Signal Routing



3.3.2 I²C Interface Routing

The I²C signals, I2C1_SCL and I2C1_SDA, must be routed following standard layout practices for digital switching signals.

- 1. Route the I2C1_SCL and I2C1_SDA traces as a pair over a reference ground plane. Each trace should have equal length to the signal source.
- 2. Use controlled 50 Ω characteristic impedance if possible.
- 3. Isolate the I2C1 SCL and I2C SDA traces with ground planes if electrical noise sources are nearby.
- 4. Avoid routing the I²C traces between power planes on an adjacent layer. If signals have to cross on adjacent layers, it is recommended they should cross perpendicular in order to prevent coupling.
- 5. Avoid routing the I²C traces next to analog and other digital signals.
- 6. Place the ADDR pull up/down resistor close to the CS40L5x device.

A typical layout for the I²C signal routing is shown in the figure below.

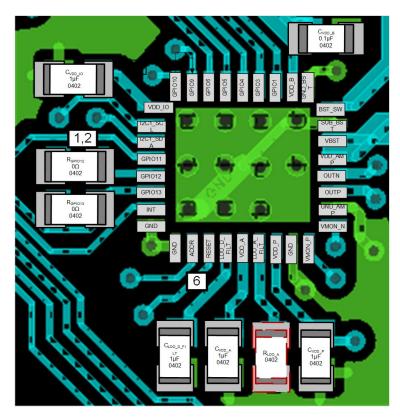


Figure 13 I2C Signal Routing



3.3.3 ASP Interface Routing

The ASP traces must be routed following standard layout practices for digital switching signals.

- 1. Use controlled 50 Ω characteristic impedance if possible.
- 2. Avoid routing these ASP traces between power planes on an adjacent layer. If signals have to cross on adjacent layers, it is recommended they should cross perpendicular in order to prevent coupling.
- 3. Avoid routing these ASP traces next to analog or digital switching signals.

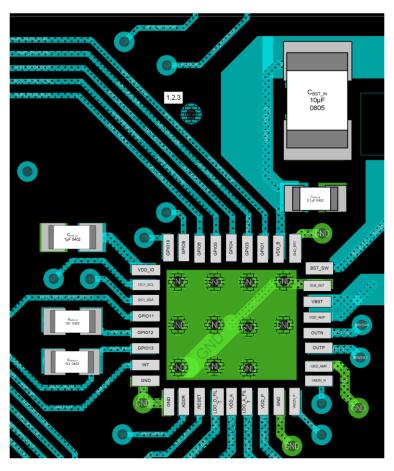


Figure 14 ASP Routing



3.3.4 GPIO Routing

The GPIO traces must be routed following standard layout practices for digital switching signals.

- 1. Use controlled 50 Ω characteristic impedance if possible.
- 2. Avoid routing these GPIO traces between power planes on an adjacent layer. If signals have to cross on adjacent layers, it is recommended they should cross perpendicular in order to prevent coupling.
- 3. Avoid routing these GPIOs traces next to analog or digital switching signals.

A typical layout for the GPIO signal routing is shown in the figure below.

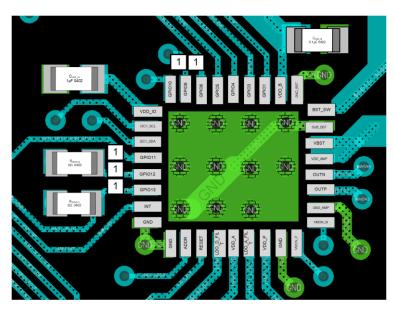


Figure 15 GPIO Signal Routing



3.3.5 Interrupt Routing

The INT trace must be routed following standard layout practices for digital switching signals.

- 1. Use controlled 50 Ω characteristic impedance if possible.
- 2. The pull up resistor can be placed either close to the CS40L5x device or the host.
- 3. Avoid routing the INT trace between power planes on an adjacent layer. If signals have to cross on adjacent layers, it is recommended they should cross perpendicular in order to prevent coupling.
- 4. Avoid routing the INT trace next to analog and digital switching signals.

A typical layout for the INT signal routing is shown in the figure below.

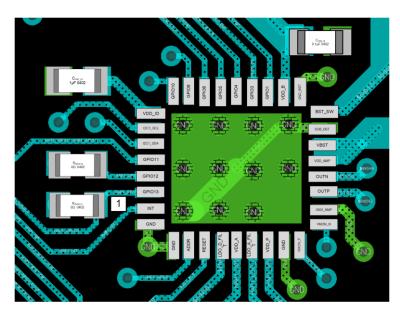


Figure 16 Interrupt (INT) Signal Routing



3.4 Output and Monitoring Routing

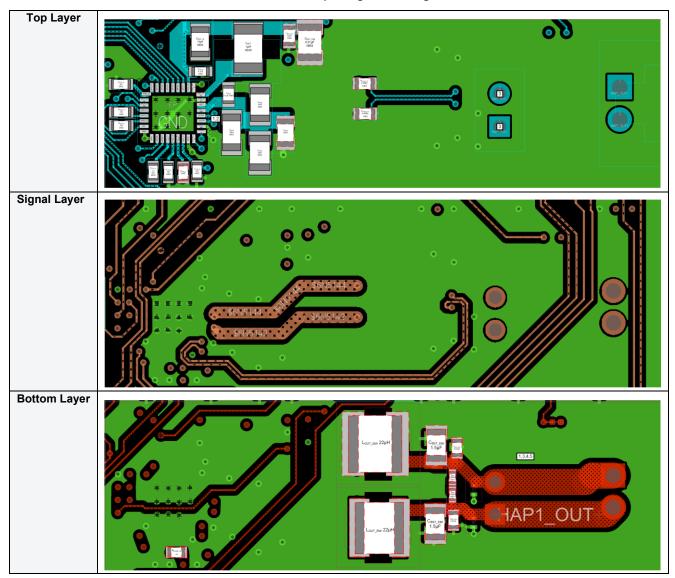
3.4.1 Output Routing

The following routing guidelines are recommended for the output signals (OUTP and OUTN).

- 1. Route OUTP and OUTN as a differential pair.
- 2. OUTP and OUTN traces can be escaped from the top layer using one or two high current vias per signal (3.5 A).
- 3. OUTP and OUTN must be routed with wide and short traces to haptic actuator (3.5 A).
- 4. The OUTP and OUTN signal traces must have low DC resistance. For best performance, the recommended DC resistance is 1% of minimum load, e.g. 0.06Ω for 6Ω load.
- 5. Avoid routing on same plane as power, and keep away from clock signals as far as possible.
- 6. Provide ground shielding around OUTP and OUTN.

A typical layout for the OUTP and OUTN signal routing is shown in the figure below.

Table 19 Output Signal Routing





3.4.2 Monitoring Routing

The VMON_P and VMON_N pins are high impedance inputs dedicated to monitoring the voltage across the haptic actuator. The current flow in these pins is very small. The following routing and component placement guidelines are recommended for these signals.

- 1. Route VMON P and VMON N as low-current traces (10 mA).
- 2. Route VMON_P and VMON_N as a differential pair.
- 3. The VMON_P and VMON_N traces must connect to OUTP and OUTN (respectively) before the EMI filter. as close as possible to the actuator (LRA/VCM) in order to ensure an accurate reading of the actuator voltage.
- 4. Provide ground shielding around VMON_P and VMON_N, and keep away from power supplies and clock signals as far as possible.
- 5. The R_{VMON} series resistors must be placed before the EMI filter (if used).

A typical layout for the VMON_P and VMON_N signal routing is shown in the figure below.

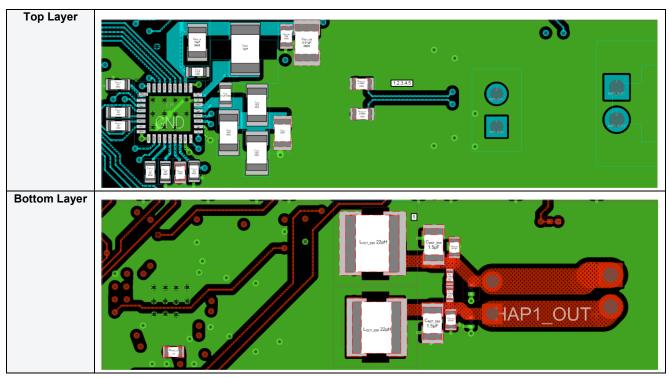


Table 20 Output Monitoring Signal Routing



3.5 EMI Filter Routing

3.5.1 Input Supply Filter

If the input EMI filter is incorporated, it is recommended that the 33 nF capacitors are mirrored around the supply line.

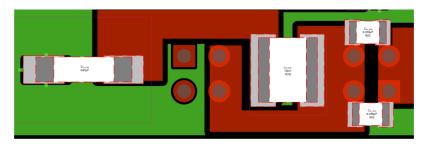


Figure 17 Input EMI Filter

3.5.2 Boost Supply Filter

The boost-supply EMI filter components should be placed as close as possible to the VDD_B pin. Additional 0.1 μ F capacitors can be added to the VBST pin.

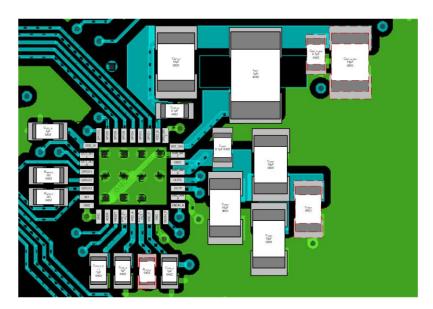


Figure 18 Boost Supply EMI Filter



3.5.3 Output EMI Filter

If the output EMI filter is incorporated, the components should be placed as close as possible to the CS40L5x. If possible, the output filter inductors should be placed on the bottom side of the board to reduce inductor-coupling interference.

Top Layer **Bottom Layer**

Table 21 Output EMI Filter

4 Revision History

Revision	Changes	
R1	• Initial release	
OCT 2025		
R2	Added pinout illustration in Section 1	
NOV 2025		
R3	Re-released without confidential restrictions	
DEC 2025		



Contacting Cirrus Logic Support

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